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# Industry 4.0 – a view on data and communication



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Aim of the Talk

↪ *It's only an attempt to **define I4.0**, point out some **technical challenges** and what kind of **research** is still necessary .*

**Aim**


- Definition
- Concepts
- Examples
- 1. Challenge
- 2. Challenge
- 3. Challenge
- 4. Challenge
- Conclusion
- References

↪ *This is not a prediction about business opportunities through Industry 4.0 (I4.0)*

- ☞ Business opportunities, social issues, and consequences for working environment are highly important and part of the I4.0 initiative, but not discussed here.
- ☞ "Prediction is very difficult, especially if it's about the future."  
[Mark Twain/Niels Bohr]

2 / 18  
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Industry 4.0: déjà-vu?



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**Definition**

Concepts

Examples

1. Challenge

2. Challenge

3. Challenge

4. Challenge

Conclusion

References

3 / 18  
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↳ **Precursor**


- ☞ Computer Integrated Manufacturing (CIM)
  - ⇒ J. Harrington, CIM, Industrial Press, 1974
  - ⇒ Hype started ~ 1984
  - ⇒ Subsystems: CAx, CNC, PPS, plant data collection

↳ **CIM = I4.0?**

**Not really**

- ☞ CIM: **Manufacturing** is controlled by Computer Systems, but not necessarily flexible; products are still “dumb”
- ☞ I4.0: **Covers the full life cycle** of a product, production is highly flexible, machines/products are “intelligent”
- ☞ **Promise of I4.0: 4<sup>th</sup> Industrial revolution<sup>1)</sup>**

CPS: Definition



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**Definition**

Concepts

Examples

1. Challenge

2. Challenge

3. Challenge

4. Challenge

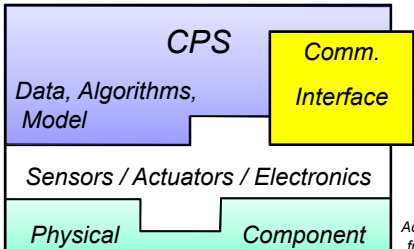
Conclusion

References

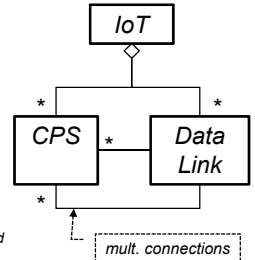
4 / 18  
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↳ **Cyber Physical System (CPS)<sup>6)</sup>**

- ☞ Is a physical system with built-in, interacting software and communication capabilities
  - ⇒ Building blocks of “Internet of Things” (IoT)
- ☞ CPS are called “intelligent” as they “know” about themselves and about their environment.
  - ⇒ Model is always in sync with phys. Component



The diagram shows a layered structure for a CPS. At the top is a blue box labeled 'CPS' containing 'Data, Algorithms, Model'. To its right is a yellow box labeled 'Comm. Interface'. Below these is a white box labeled 'Sensors / Actuators / Electronics'. At the bottom is a green box labeled 'Physical Component'.



The UML class diagram shows 'IoT' at the top with a diamond relationship to 'CPS' and 'Data Link'. 'CPS' and 'Data Link' have a 1-to-many relationship. 'Data Link' has a self-relationship labeled 'mult. connections' in a dashed box. Asterisks (\*) indicate multiplicity.

Adapted from <sup>8)</sup>

**Industry 4.0: Definition**

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**Definition**

Concepts

Examples

1. Challenge

2. Challenge

3. Challenge

4. Challenge

Conclusion

References

5 / 18

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*↪ Industry 4.0 (I4.0)*

☞ Is the name for a fully digitalized, automated, and flexible product lifecycle, notably production technology,

e.g. using CPS to build a “smart factory”

⇒ I4.0 covers the whole product lifecycle <sup>1,7)</sup>

⇒ Production is adaptive (modular, flexible) with

- interoperable, autonomous CPSs
- CPSs take decentralized decisions (in real-time!)
- products itself are also a kind of CPS<sup>2)</sup>, i.e.
- I4.0 lies the grounds for machines that create new (and better) machines to replace themselves.

**Industry 4.0 vs CPS vs CIM**

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**Definition**

Concepts

Examples

1. Challenge

2. Challenge

3. Challenge

4. Challenge

Conclusion

References

6 / 18

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*↪ I4.0 refers to a digitalized, flexible production with autonomous manufacturing machines and business services.*

*Products know about itself during the whole life cycle*

*↪ CPS relates to physical things with computing and communication capabilities which can be components of I4.0*

*↪ CIM is a computer supported manufacturing with hierarchical control*

```

classDiagram
    class Industry40[Industry 4.0]
    class CIM
    class CPS
    class CPSsubsys[CPS subsys]
    class I40comp[I4.0 component2)]

    Industry40 --|> CIM
    Industry40 o-- CPS
    CPS o-- "*" CPSsubsys
    CPS <|-- I40comp
            
```

CIM is a subset of I4.0 in terms of the completeness of the model

3

**14.0 Design Principals**

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Definition

**Concepts**

Examples

1. Challenge

2. Challenge

3. Challenge

4. Challenge

Conclusion

References

↳ *Design principals<sup>9)</sup> are*

- ☞ Decentralized decisions
- ☞ Interconnection and integration
- ☞ Information transparency
- ☞ Technical assistance for humans

14.0 product lifecycle and 3 kinds of integration<sup>3)</sup>:

Problem: End-to-End and Horizontal integration are not orthogonal  
→ some elements are entangled

7 / 18  
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**Reference Architecture Model Industry 4.0 (RAMI 4.0)**

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Definition

**Concepts**

Examples

1. Challenge

2. Challenge

3. Challenge

4. Challenge

Conclusion

References


↳ *The 3-dimensional framework RAMI 4.0<sup>2)</sup>*

- ☞ Covers different aspects (layers), product life cycle, and the position of I 4.0 elements in the Industry hierarchy

Problem: Many crosscutting functions, aspects and elements exist  
→ „separation of concerns“ is not always possible

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**Example: flexible Production with lot size 1**

  
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Definition

Concepts

**Examples**

1. Challenge

2. Challenge

3. Challenge

4. Challenge

Conclusion

References

9 / 18  
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### Smart factory production system

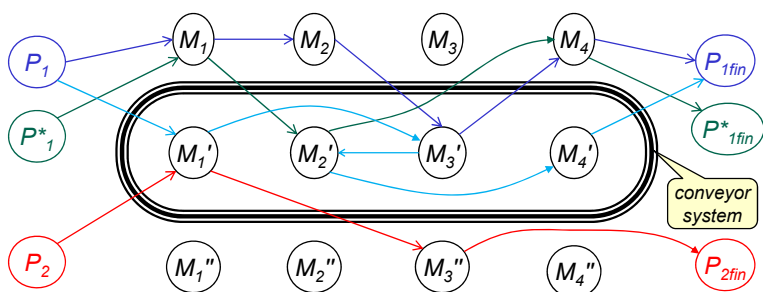



Figure adapted and extended from <sup>3)</sup>

**Legend:**  $P_{x[fin]}$  = [final] Product x,  $P^*_x$  = Variant of Product x  
 $M_x^{[i]}$  = Machines x <sup>[i]</sup> with the same capabilities

**Multiple routes:**

- standard route A,
- alternative route B (e.g. if  $M_1$  is broken and all  $M_2$  are in use (only possible if process steps of  $M_2$  and  $M_3$  are interchangeable),
- route A\* for product variant  $P^*1$  (step  $M_3$  (e.g. painting) is skipped),
- route C for other product  $P_2$

**Real World Example**

  
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Definition

Concepts

**Examples**

1. Challenge

2. Challenge

3. Challenge

4. Challenge


Conclusion


References

10 / 18  
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
### Trumpf

- ☞ World leading company for advanced, high precision, industrial Machine Tools, [Laser Technology](#), and Electronics
- ☞ Is a protagonist of I4.0 technology in Germany
  - ⇒ Develops and uses I4.0 Technology for its own “smart factory”
  - ⇒ Member of Allianz I4.0, I4.0 working group of BMBF, and Smart Data Innovation
- ☞ I4.0 related products
  - ⇒ [TruConnect](#): Digitized, networked, and automated order processing
  - ⇒ [SYNCHRO](#): Just-in-time production control and Continuous Improvement Process (Kaizen)
- ☞ [www.trumpf.com](http://www.trumpf.com)
- ☞ <https://www.youtube.com/watch?v=ewjIVUri1s>

 Reutlingen University  Aim Definition Concepts <b>Examples</b> 1. Challenge 2. Challenge 3. Challenge 4. Challenge Conclusion References  11 / 18 © F. Laux	Real World Example
	<p><b>Festo</b></p> <ul style="list-style-type: none"> <li>☞ Leading world-wide supplier of automation technology, robotic (bionic), and technical education (didactic learning and simulation factory)</li> <li>☞ Is a protagonist of I4.0 technology in Germany                     <ul style="list-style-type: none"> <li>⇒ Develops valves, pneumatic and servo drives, controller and sensors for factory and process automation</li> <li>⇒ Coauthored chap. 6 of <sup>2)</sup> and contributor to <sup>1)</sup></li> </ul> </li> <li>☞ I4.0 related products and projects                     <ul style="list-style-type: none"> <li>⇒ “Intelligent” components: self configuring pneumatic conveyor (<a href="#">WaveHandling</a>), produced at Scharnhausen I4.0 Technology Plant: 66k m<sup>2</sup>, 1200 employees</li> <li>⇒ MetamoFAB<sup>12)</sup>: developing solutions to enable a metamorphosis into intelligent and networked factories</li> <li>⇒ OPAK: open engineering platform for autonomous, mechatronic automation components</li> <li>⇒ <a href="#">BionicANTs</a>: cooperative behavior, highly integrated individual systems used to solve a common task → <a href="#">SmartBird</a></li> </ul> </li> <li>☞ <a href="http://www.festo.com">www.festo.com</a>;  <a href="http://www.festo.com/group/de/cms/10225.htm">www.festo.com/group/de/cms/10225.htm</a>  <a href="http://www.youtube.com/watch?v=3SKiH8N8D6w">www.youtube.com/watch?v=3SKiH8N8D6w</a></li> </ul>

 Reutlingen University  Aim Definition Concepts Examples <b>1. Challenge</b> 2. Challenge 3. Challenge 4. Challenge Conclusion References  12 / 18 © F. Laux	1. Challenge: (Wireless) Interconnection in Real-time
	<p><b>Collaborating machines/robots need real-time response guaranties.</b></p> <ul style="list-style-type: none"> <li>☞ Direct links                     <ul style="list-style-type: none"> <li>⇒ <b>How to master the many to many links?</b> → <math>O(n^2)</math> problem</li> <li>⇒ <b>Wireless LAN</b> → signal collisions, no resp.-time guaranty</li> </ul> </li> <li>☞ Internet protocols are not designed for real-time communication                     <ul style="list-style-type: none"> <li>⇒ <b>How can hard real-time limits be assured?</b> <ul style="list-style-type: none"> <li>• Protocols on top of TCP/IP deliver only “soft” real-time.</li> <li>• Synchronous protocols like ProfiNet IRT (1 ms cycle) are not compatible with CSMA/CD. (see <sup>10)</sup>)</li> </ul> </li> </ul> </li> <li>☞ In production environments there is a high level of EMI (electro-magnetic interference)                     <ul style="list-style-type: none"> <li>⇒ <b>How can EMI disturbances be mastered in production environment?</b> → mobile assistance systems produce additional interferences</li> </ul> </li> </ul>

**2. Challenge: The Data Integration Problem**



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
Aim  
Definition  
Concepts  
Examples  
1. Challenge  
**2. Challenge**  
3. Challenge  
4. Challenge  
Conclusion  
References

13 / 18  
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↪ **Taming the data flood**

- ☞ I4.0 recommendations:
  - ⇒ Administrative data should be stored with scalable cloud technology.
  - ⇒ Operative/machine data should be stored locally.
- ☞ Data from many dispersed sources need to be integrated. This requires a consolidated data model.
  - ⇒ **Is there an enterprise data model?** → semantic of data
- ☞ Many decisions need support from big data analysis
  - ⇒ **Can the data flood be analyzed in time?** → data stream analysis
- ☞ Workflow and Process data need transactional reliability. Not only storing (logging) of data but also structuring and high performance transactional processing is required. Distributed decision is needed in real-time.
  - ⇒ **Are the traditional protocols (locking, 2PC, buffering, etc) sufficient for the performance?**

**3. Challenge: Decentralized Intelligence**



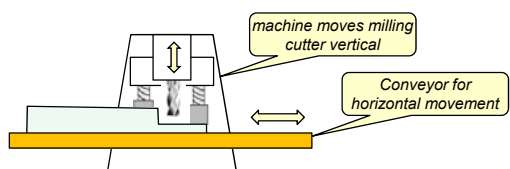
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Aim  
Definition  
Concepts  
Examples  
1. Challenge  
2. Challenge  
**3. Challenge**  
4. Challenge  
Conclusion  
References


14 / 18  
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↪ **Where and how is the knowledge distributed?**

- ☞ Machines/Robots have to collaborate to achieve a joint function or to take a decentralized decision
  - ⇒ **Who knows about the joint functions/possibilities?**
    - Example: Planning with a milling machine and a conveyor
      - the milling machine has limited movement, with the help of a conveyor a part can be planed for arbitrary length
  - ⇒ the knowledge about this joint function needs to be stored somewhere (the conveyor is “misused” as a traverse feed in this case)



- ⇒ **What are the strategies for creating joint functions?**
  - is there a voting, a judge in case of draw, a priority, try-and-error?



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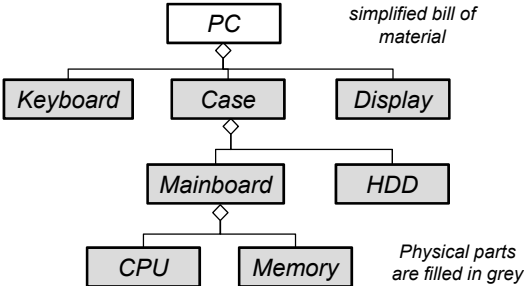
- Aim
- Definition
- Concepts
- Examples
- 1. Challenge
- 2. Challenge
- 3. Challenge
- 4. Challenge**
- Conclusion
- References

15 / 18  
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### 4. Challenge: Aggregated Knowledge

↪ *A product knows about itself (properties, purpose, etc.)*


- ☞ **Where is this information located?**  
→ it needs to be attached to a physical part<sup>4)</sup> (the PC is an aggregate, not a physical part).
- ☞ **What if the information is distributed?** → parts can be used for many different products



*simplified bill of material*

*Physical parts are filled in grey*

- ☞ **What happens if the product is disassembled?**  
→ is the product information lost? BoM stored?



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- Aim
- Definition
- Concepts
- Examples
- 1. Challenge
- 2. Challenge
- 3. Challenge
- 4. Challenge
- Conclusion**
- References

16 / 18  
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
### Conclusion


↪ **Industry 4.0**

- ☞ Makes a lot size of 1 possible (not always desirable)
  - ⇒ Questionable business value for (cheap) mass products
- ☞ allows new business models
- ☞ Is more an evolution of CIM than an industrial revolution
  - ⇒ See <sup>5)</sup> and <sup>11)</sup> for critical voices
- ☞ Research still necessary
- ☞ Substantial investment needed
- ☞ Huge social impact on employees

↪ *Industry 4.0 hype seems to increase with “additive production” (3D-Printing)*



 Reutlingen University  Aim Definition Concepts Examples 1. Challenge 2. Challenge 3. Challenge 4. Challenge Conclusion <b>References</b>  17 / 18 © F. Laux	<b>References</b>
	1) <i>Kagermann, Wahlster, Helbig (Hrsg); Umsetzungsempfehlungen für das Zukunftsprojekt Industrie 4.0, 2013, URL: <a href="https://www.bmbf.de/files/Umsetzungsempfehlungen_Industrie4_0.pdf">https://www.bmbf.de/files/Umsetzungsempfehlungen_Industrie4_0.pdf</a></i>
	2) <i>Bitkom, VDMA, ZVEI (Hrsg); Umsetzungsstrategie Industrie 4.0, 2015, URL: <a href="https://www.bitkom.org/Bitkom/Publikationen/Umsetzungsstrategie-Industrie-40.html">https://www.bitkom.org/Bitkom/Publikationen/Umsetzungsstrategie-Industrie-40.html</a></i>
	3) <i>Wang, Wan, Li, and Zhang; „Implementing Smart Factory of Industrie 4.0: An Outlook“, Intl. Journal of Distributed Sensor Networks, Vol. 20, Hindawi Publ. Corp., 2015</i>
	4) <i>Höme, Grützner, Hadlich, Diedrich, Schnäpp, Arndt, Schnieder; „Semantic Industry: Herausforderungen auf dem Weg zur rechnergestützten Informationsverarbeitung der Industrie 4.0“, in Automatisierungstechnik 2015, vol. 63(2), pp. 74-86, DeGruyter Oldenbourg, 2015</i>
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	6) <i>Riedl, Zipper, Meier, Diedrich; „Cyber-physical systems alter automation architectures“, in Annual Reviews in Control, Elsevier Ltd., 2014</i>
	7) <i>Posada, Toro, Darandiaran, Oyarzun, Stricker, de Amicis, Pinto, Eisert, Döllner, Vallarino Jr.; „Visual Computing as a Key Enabling Technology for Industrie 4.0 and Industrial Internet“, IEEE Computer Graphics and Applications, 2015</i>
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	9) <i>Hermann, Pentek, Otto; Design Principles for Industrie 4.0 Scenarios, 49th Hawaii International Conference on System Sciences, IEEE, 2016</i>
	10) <i>Frank Dopatka, Ein Framework für echtzeitfähige Ethernet-Netzwerke in der Automatisierungstechnik mit variabler Kompatibilität zu Standard-Ethernet, Dissertation, Univ. Siegen, 2008, URL: <a href="http://www.bs.informatik.uni-siegen.de/forschung/Dopatka.pdf">http://www.bs.informatik.uni-siegen.de/forschung/Dopatka.pdf</a></i>
	11) <i>Volker Spanier (Leiter Factory Automation, Fa. Epson), Interview Epson: Industrie 4.0 gleich CIM?, Produktion, Juli 2012, URL: <a href="http://www.produktion.de/nachrichten/unternehmen-maerkte/interview-epson-industrie-4-0-gleich-cim-116.html">http://www.produktion.de/nachrichten/unternehmen-maerkte/interview-epson-industrie-4-0-gleich-cim-116.html</a></i>
	12) <i>Niggemann, Henning, Schriegel, Otto, Anis; „Models for Adaptable Automation Software An Overview of Plug-and-Produce in Industrial Automation“ in 11th Dagstuhl Workshop Modellbasierte Entwicklung eingebetteter Systeme (MBEES), Dagstuhl, Germany, Mar 2015</i>

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